

Optimal incentives for socio-technical systems

Dario Paccagnan

Acknowledgements



Rahul Chandan



Bryce Ferguson



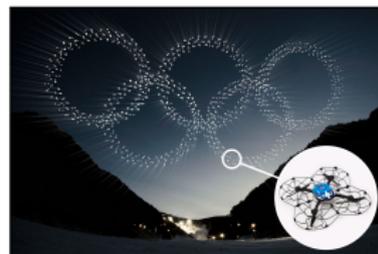
Jason Marden



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SWISS NATIONAL SCIENCE FOUNDATION



Multiagent Coordination



Social Systems ← -- Socio-technical Systems -- → Engineered Systems

Multiagent Coordination



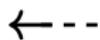
Social Systems



Socio-technical Systems



Engineered Systems



- ▷ Traffic
- ▷ Energy Markets

- ▷ Resource Allocation
- ▷ Sensor Coverage

Multiagent Coordination

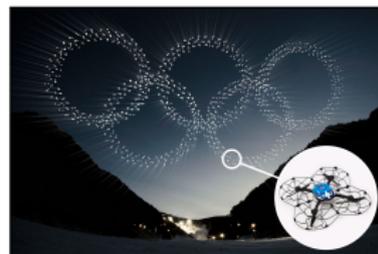


Social Systems



Socio-technical Systems

- ▷ Traffic
- ▷ Energy Markets



Engineered Systems

- ▷ Resource Allocation
- ▷ Sensor Coverage

Multiagent Coordination

Central Goal: coordinate socio-technical systems to desirable behaviour



Social Systems



Socio-technical Systems

- ▷ Traffic
- ▷ Energy Markets



Engineered Systems

- ▷ Resource Allocation
- ▷ Sensor Coverage

Socio-technical systems

Infrastructure



Socio-technical systems

Infrastructure

+

Users Behavior



Socio-technical systems

Infrastructure

+

Users Behavior

=

Performance



Socio-technical systems

Infrastructure



+

Users Behavior



=

Performance



Q: How to incentivize desirable system-level behaviour?

Socio-technical systems

Infrastructure



+

Users Behavior



=

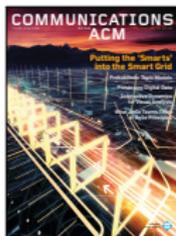
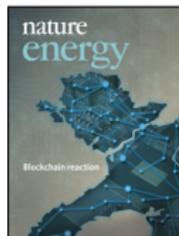
Performance



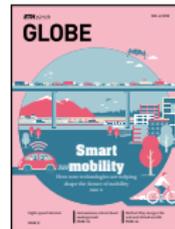
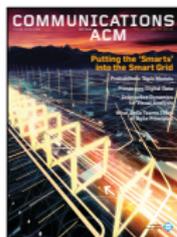
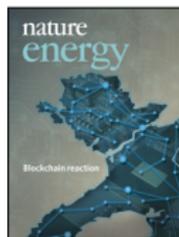
Mechanism

Q: How to incentivize desirable system-level behaviour?

Socio-technical systems are pervasive ...



Socio-technical systems are pervasive ...



Paradigm shift: technology now interacts with human users

... and come with key challenges

Policy paper

The Grand Challenges

Updated 13 September 2019

Contents

[Artificial Intelligence and data](#)

[Ageing society](#)

[Clean growth](#)

[Future of mobility](#)

The **4 Grand Challenges** are focused on the trends which will transform our future:

- Artificial Intelligence and data
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... and come with key challenges



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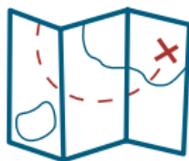
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⇒ **an interdisciplinary endeavour:**

computer science, control theory, optimization, economics, social sciences, urban planning, ...



ROADMAP

1. Mechanisms for smart mobility: congestion pricing
~> optimal tolling mechanisms
2. Outlook and opportunities

Congestion is soaring...



New York



London



Beijing



Nairobi

Congestion is soaring...

\$100 Billion Cost of Traffic Congestion in Metro New York

Traffic congestion will be a \$100 billion drag on the New York metro area's economy over the next five years unless something is done to discourage cars and trucks from clogging the streets and highways of the region during the busiest times of the day, according to a study conducted by HDR for the Partnership for the New York City. The Manhattan central business district, where a quarter of regional economic activity is concentrated, is the primary source of traffic congestion across the region. Excess congestion has increased 50 percent since the Partnership and HDR conducted an initial analysis in 2006, rising to a cost of \$20 billion annually.

\$20 billion annually includes:



\$9.17 billion

is the annual cost of delay in commuting time and work-related travel, representing the largest share of the total cost of congestion.

People who work in Queens and Manhattan are hardest hit by traffic delays, costing the metropolitan area businesses \$1,000 to \$1,000 a year.



CHINA DAILY 中国日报

Traffic jams cost average Beijinger \$1,126 annually

By Meng Jing (china-daily.com.cn)

Updated: 2018-01-20 10:44



The Fourth Ring Road in Beijing in a morning rush hour. City authorities are working on solutions to ease the pressures on traffic in the city. (Shao Zhenyi / For China Daily)

The Telegraph

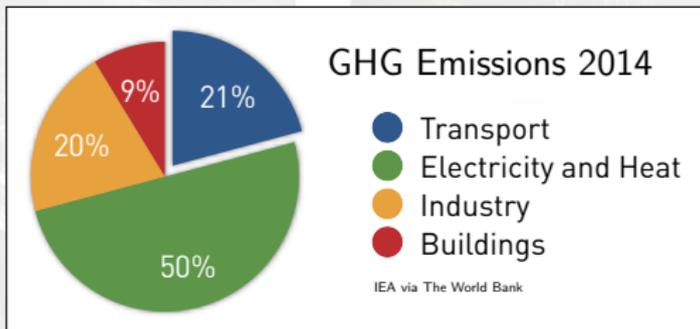
Traffic jams cost the average motorist more than £1,000 a year



Source: Ipsos Mori. Cost of £1000 each. www.telegraph.co.uk

New York

London



Beijing

Nairobi

...and tolls being proposed to alleviate the issue

The New York Times

Over \$10 to Drive in Manhattan? What We Know About the Congestion Pricing Plan



The price of entering Manhattan could reach as much as \$25 for some drivers, [Trent Luster for The New York Times](#).

Forbes

Most Cities Will Have To Introduce Congestion Charging, Say Experts At Global Transit Conference

Center for Cities



100% job and safety on the highway at outside Stockholm - [gsm](#)

TRANSPORT FOR LONDON

Plan a journey Status updates Maps Fares Help & contacts

Driving Congestion Charge

Congestion Charge

The Congestion Charge is an **£1.50 daily charge for driving a vehicle** within the charging zone **between 07:00 and 18:00, Monday to Friday**. The easiest way to pay is by setting up Auto Pay. Exemptions and discounts are available too.

You'll also need to check if your vehicle is affected by the [Ultra Low Emission Zone \(ULEZ\)](#).

The cost of the daily Congestion Charge payments is cut by up to £1 if you [set up Auto Pay](#). There's an annual registration charge of £10 for each vehicle you register.

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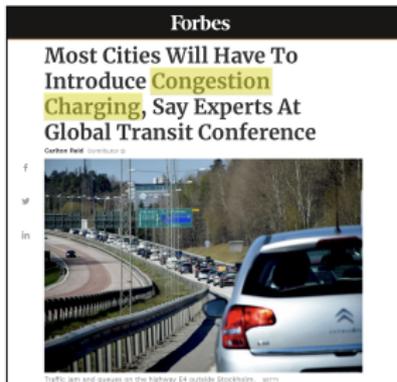
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▷ Current: blunt policies

...and tolls being proposed to alleviate the issue



- ▷ Current: blunt policies
- ▷ Future: fine grained + adaptive pricing using location data

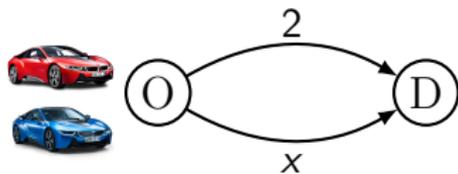
How do we design fine grained and adaptive congestion pricing?

Congestion pricing in a nutshell

- ▷ **Problem:** collective behaviour of selfish agents is often inefficient

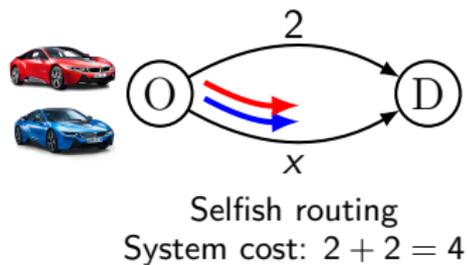
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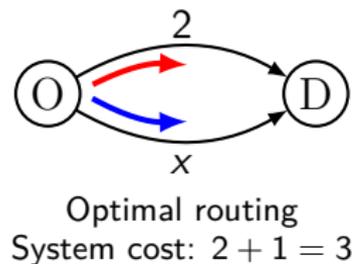
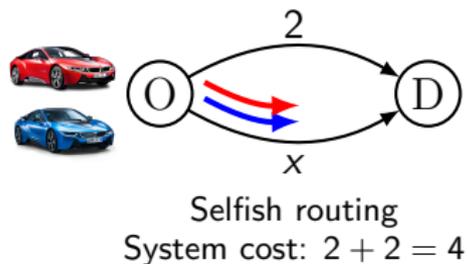
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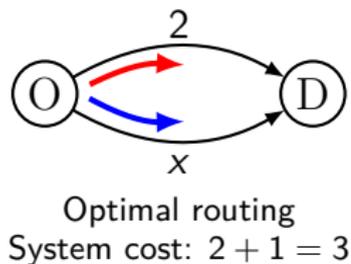
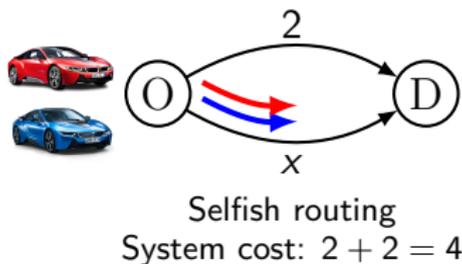
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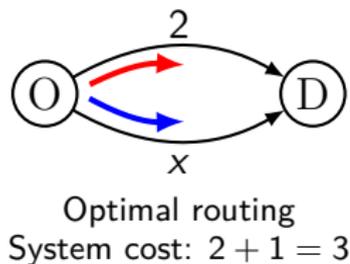
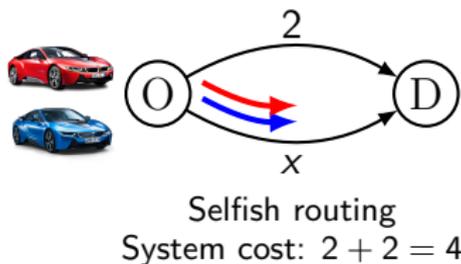
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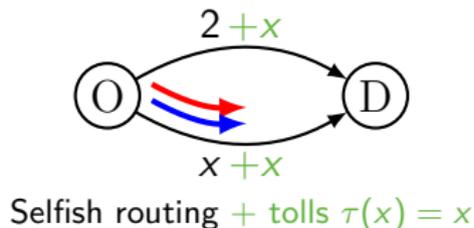
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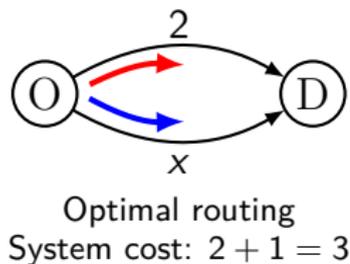
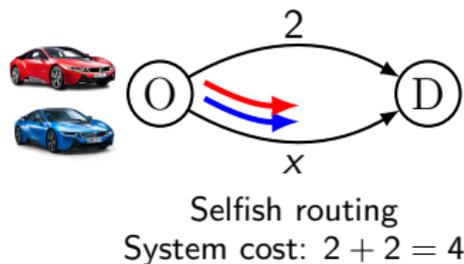


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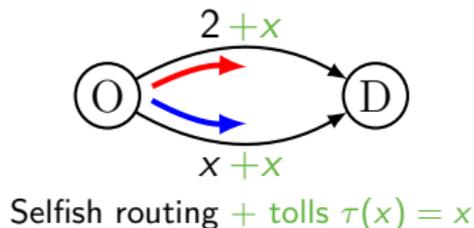


Congestion pricing in a nutshell

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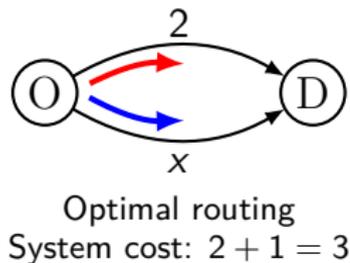
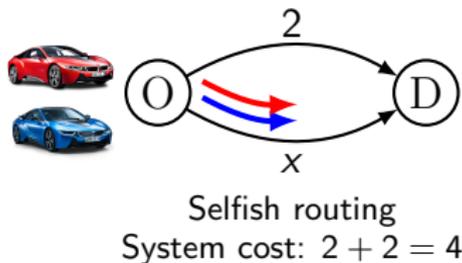


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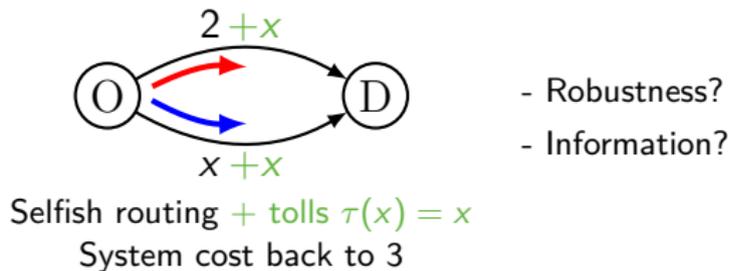


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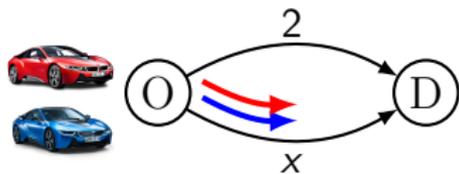


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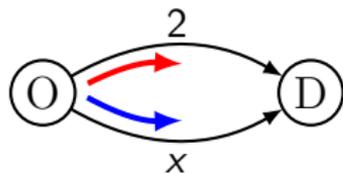


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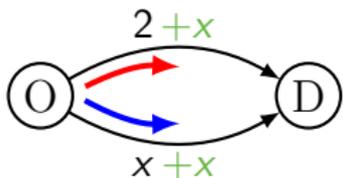


Selfish routing
System cost: $2 + 2 = 4$



Optimal routing
System cost: $2 + 1 = 3$

- ▷ **Congestion pricing:** influence behavior to minimize total traveltime



Selfish routing + tolls $\tau(x) = x$
System cost back to 3

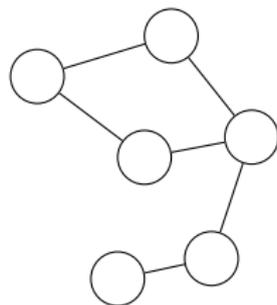
- Robustness?
- Information?

Q: how to compute “optimal” tolls?

Routing on a network - model

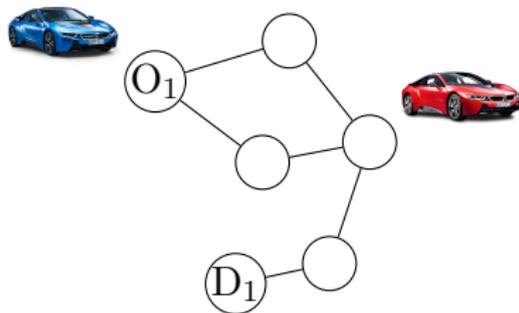
Routing on a network - model

- graph



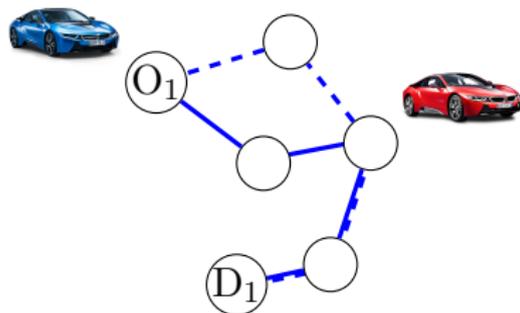
Routing on a network - model

- graph
- agent i , $\{O_i, D_i\}$



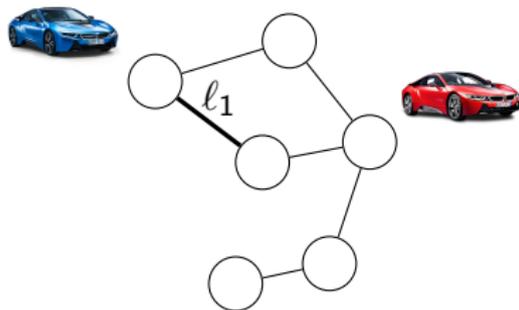
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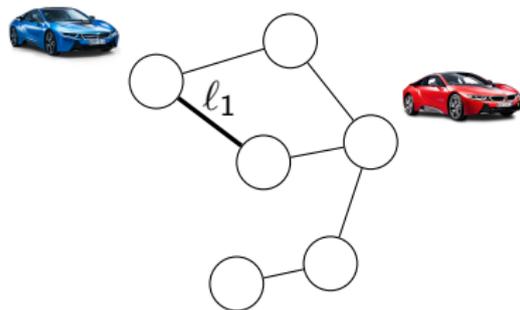
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- latency functions $\ell_e(|p|_e)$



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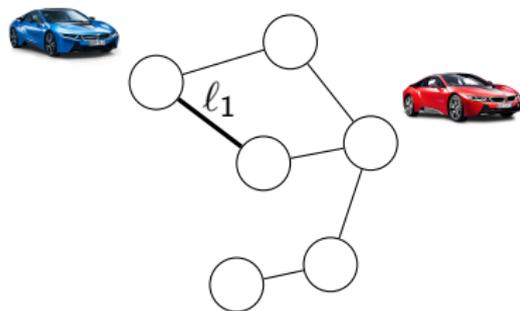


agents' costs

$$C_i(p) = \sum_{e \in p_i} \ell_e(|p|_e)$$

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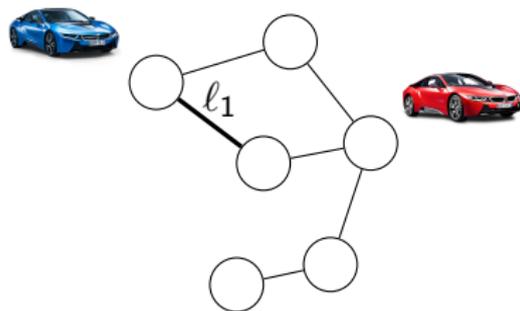
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total traveltime

$$TT(p) = \sum_{e \in E} |p|_e \ell_e(|p|_e)$$

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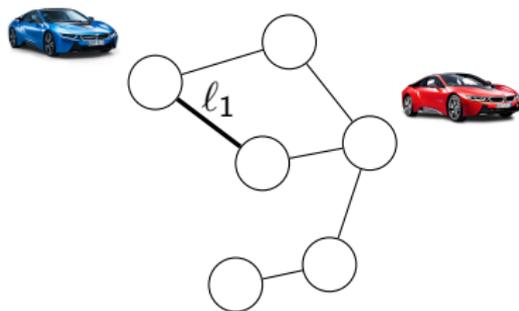
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Inefficiency =

$$\frac{\text{total travel time in worst equilibrium}}{\text{minimum total travel time}}$$

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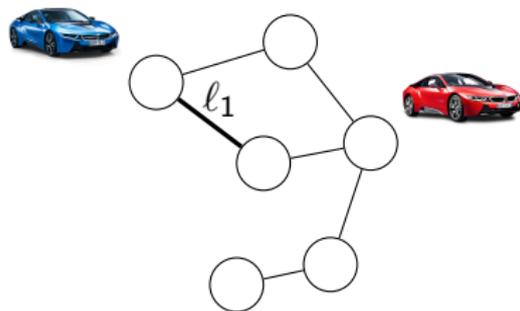
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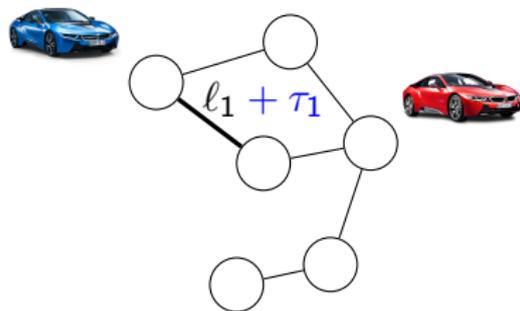
total traveltime

$$TT(p) = \sum_{e \in E} |p|_e \ell_e(|p|_e)$$

$$\text{Price of Anarchy} = \max_{\text{set of instances}} \frac{\text{total travel time in worst equilibrium}}{\text{minimum total travel time}}$$

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agents' costs

$$C_i(p) = \sum_{e \in p_i} \ell_e(|p|_e) + \tau_e(|p|_e)$$

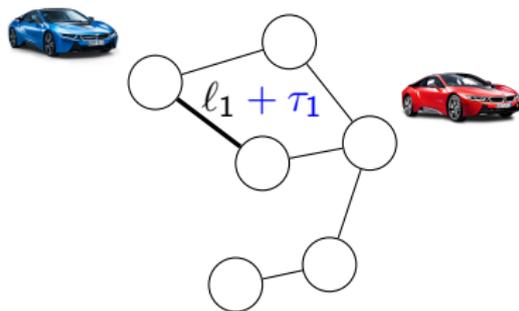
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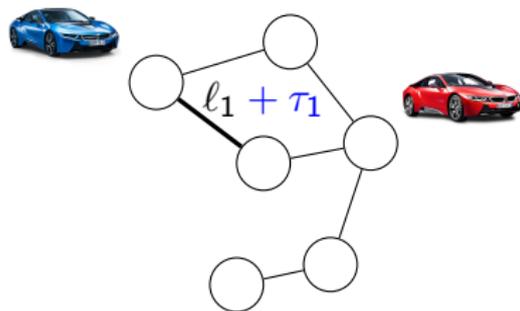
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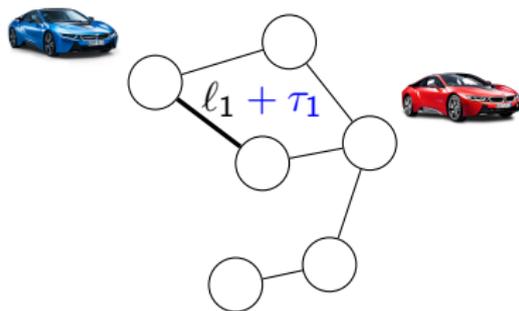
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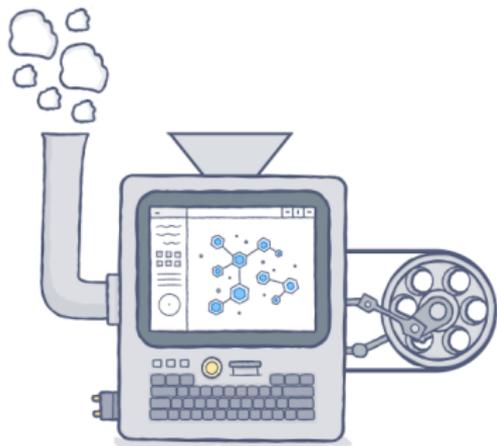
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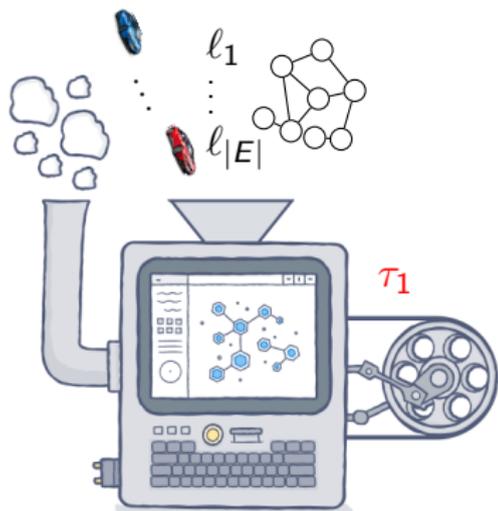
Goal: design tolls that *minimize* price of anarchy

How much information to compute each toll?



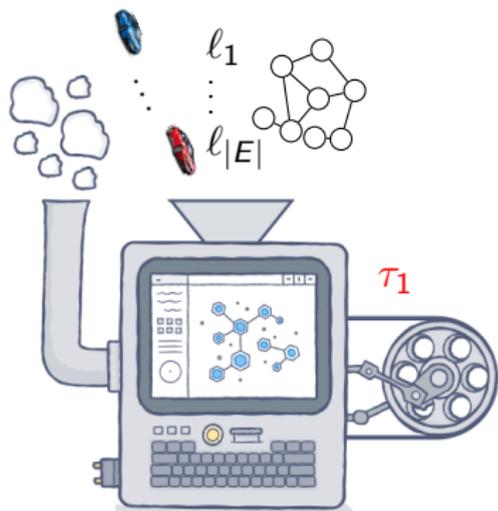
full info: $\tau_e = T(\{O_i, D_i\}, \{l_e\}, \text{graph})$

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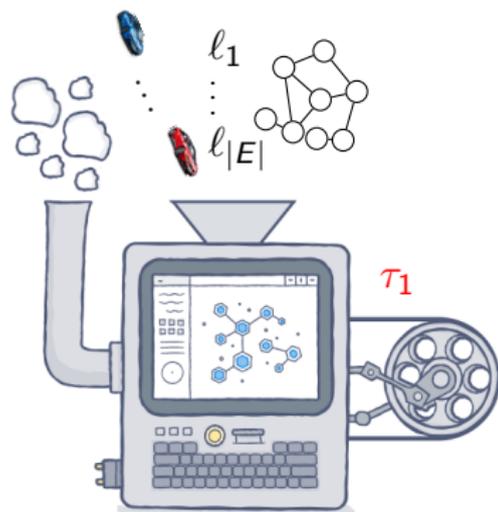


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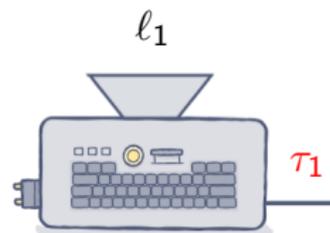


local info: $\tau_e = T(l_e)$

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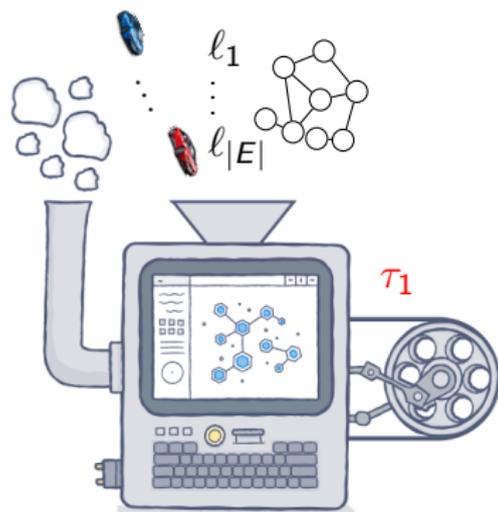


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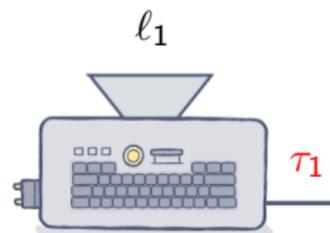


full info: $\tau_e = T(\{O_i, D_i\}, \{l_e\}, \text{graph})$

+ more performance

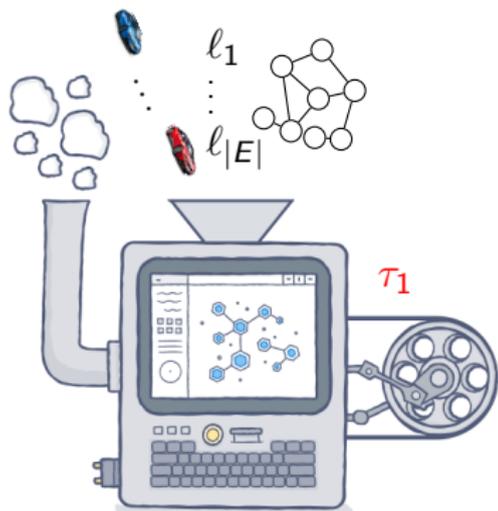
- requires more computation

- not robust



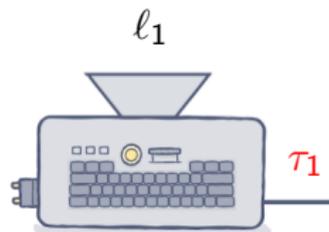
local info: $\tau_e = T(l_e)$

How much information to compute each toll?



full info: $\tau_e = T(\{O_i, D_i\}, \{l_e\}, \text{graph})$

- + more performance
- requires more computation
- not robust



local info: $\tau_e = T(l_e)$

- less performance
- + simpler computation
- + robust

History and related works

- ▷ **Congestion games (Rosenthal 1973)**

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applied to: road-traffic, electricity markets, load balancing, network design, sensor allocation, wireless data networks

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- ▷ **Price of anarchy (Koutsoupias, Papadimitriou 1999)**

Worst-Case Equilibria

Elias Koutsoupias¹ and Christos Papadimitriou²

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Abstract. In a system in which noncooperative agents share a common resource, we propose the ratio between the worst possible Nash equilibrium and the social optimum as a measure of the effectiveness of the system. Deriving upper and lower bounds for this ratio in a model in which several agents share a very simple network leads to some interesting mathematics, results, and open problems.

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How Bad Is Selfish Routing?

TIM ROUGHGARDEN AND ÉVA TARDOS

Cornell University, Ithaca, New York

Abstract. We consider the problem of routing traffic to optimize the performance of a congested network. We are given a network, a rate of traffic between each pair of nodes, and a latency function for each edge specifying the time needed to traverse the edge given its congestion; the objective is to route traffic such that the sum of all travel times—the total latency—is minimized.

In many settings, it may be expensive or impossible to regulate network traffic so as to implement an optimal assignment of routes. In the absence of regulation by some central authority, we assume that each network user routes its traffic on the minimum-latency path available to it, given the network congestion caused by the other users. In general such a “selfishly motivated” assignment of traffic to paths will not minimize the total latency; hence, this lack of regulation carries the cost of decreased network performance.

In this article, we quantify the degradation in network performance due to unregulated traffic. We

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↪ quantification: Papadimitriou, Tardos, Roughgarden, Nisan, Suri, Vazirani, Stier-Moses, Anshelevich, Christodoulou, Aland, Gairing, ...

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How Bad Is Selfish Routing?

TIM ROUGHGARDEN AND ÉVA TARDOS

The Price of Anarchy of Finite Congestion Games^{*}

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ABSTRACT

We consider the price of anarchy of pure Nash equilibria in congestion games with linear latency functions. For congestion games, the price of anarchy of nonatomic social cost is $\frac{4}{3} \sqrt{N}$, where N is the number of players. For all other cases of congestion or nonatomic games and for both maximum and average social cost, the price of anarchy is $\frac{5}{2}$. We extend the results to latency functions that are polynomial of bounded degree. We also extend some of the results to mixed Nash equilibria.

In what happens in more general networks or even in more general congestion games that have no underlying network, Roughgarden and Tucker [RT04] give the answer for the case where the players control a negligible amount of traffic. But what happens in the discrete case? This is the question that we address in this paper.

Congestion games, introduced by Rosenthal [Ros80] and studied in [RT04], is a natural general class of games that provide a striking contrast between the two models studied in [RT04] and [RT02]. The possible link model of [RT02] is a special case of congestion games (with singleton strategies but with

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in which noncooperative agents share a common ratio between the worst possible Nash equilibrium as a measure of the effectiveness of the and lower bounds for this ratio in a model in a very simple network leads to some interesting mathematics, results, and open problems.

⇒ quantification: Papadimitriou, Tardos, Roughgarden, Nisan, Suri, Vazirani, Stier-Moses, Anshelevich, Christodoulopoulos, Aland, Gairing, ...

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Exact Price of Anarchy for Polynomial Congestion Games *
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Department of Computer Science, Electrical Engineering and Mathematics
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Abstract. We show exact values for the price of anarchy of weighted and unweighted congestion games with polynomial latency functions. The given values also hold for weighted and unweighted network congestion games.

Worst-Case Equilibria
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The diagram illustrates the historical development of congestion game research through overlapping paper titles and authors:

- How Bad Is Selfish Routing?** by TIM ROUGHGARDEN AND ÉVA TARDOS.
- The Price of Anarchy of Finite Congestion Games*** by George Christodoulou (National and Kapodistrian University of Athens) and Elias Koutsoupias (National and Kapodistrian University of Athens).
- Exact Price of Anarchy for Polynomial Congestion Games *** by Sebastian Aland, Dominic Dumrauf, Martin Gairing, Burkhard Monien, and Florian Schoppmann (Department of Computer Science, Electrical Engineering and Mathematics, University of Paderborn).
- Intrinsic Robustness of the Price of Anarchy** by Tim Roughgarden (Department of Computer Science, Stanford University).
- Selfish Load Balancing and Atomic Congestion Games¹** by Subhash Suri, Caba D. Toth, and Yunhong Zhou (Research Academic Computer Technology Institute and Dept. of Computer Engineering and Informatics, University of Patras).
- Taxes for Linear Atomic Congestion Games*** by Ioannis Caragiannis, Christos Kallamanis, and Panagiotis Kanellopoulos (Research Academic Computer Technology Institute and Dept. of Computer Engineering and Informatics, University of Patras).

Abstract. We study congestion games where players aim to access a set of resources. Each player has a set of possible strategies and each resource has a function associating the latency it incurs to the players using it. Players are non-cooperative and each wishes to follow strategies that minimize her own latency with no regard to the global optimum. Previous work has studied the impact of this selfish behavior to system

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Intrinsic Robustness of the Price of Anarchy
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Department of Computer Science
Stanford University

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Siddhesh Suri,² Caba D. Toth,³ and Yunhong Zhou⁴

Taxes for Linear Atomic Congestion Games*
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- ⇒ optimization: Wierman, Roughgarden, Marden, Caragiannis, Gairing, Biló, ...

Preview of the results

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Main result: first solution to design of optimal tolls
in congestion games (via linear programming)

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- ▷ **Example:** prices of anarchy for polynomial latencies of degree d

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▷ **Example:** prices of anarchy for polynomial latencies of degree d

d	Untolled [1, 2, 3, ...]			
1	2.50			
2	9.58			
3	41.54			
4	267.64			
5	1513.57			

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↪ Approach recovers altogether [1, 2, 3, ...] + produces novel results

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Main result: first solution to design of optimal tolls in congestion games (via linear programming)

▷ **Example:** prices of anarchy for polynomial latencies of degree d

d	Untolled [1, 2, 3, ...]	Lower bound full info [4, 5]	
1	2.50	2	
2	9.58	5	
3	41.54	15	
4	267.64	52	
5	1513.57	203	

↪ Approach recovers altogether [1, 2, 3, ...] + produces novel results

[1] Christodoulou, Koutsoupias, STOC 05;

[2] Aland et al., STACS 06;

[3] Roughgarden, STOC09 and JACM 15

[4] Caragiannis, Kaklamanis, Kanellopoulos, ESA 06;

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▷ **Example:** prices of anarchy for polynomial latencies of degree d

d	Untolled [1, 2, 3, ...]	Lower bound full info [4, 5]		Optimal toll local info	
1	2.50	2		2.01	
2	9.58	5		5.10	
3	41.54	15		15.55	
4	267.64	52		55.45	
5	1513.57	203		220.40	

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↪ Tolls based on local info \approx tolls with full info

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▷ **Example:** prices of anarchy for polynomial latencies of degree d

d	Untolled [1, 2, 3, ...]	Lower bound full info [4, 5]	 Optimal toll local info	 Optimal toll local info & constant
1	2.50	2	2.01	2.15
2	9.58	5	5.10	5.33
3	41.54	15	15.55	18.36
4	267.64	52	55.45	89.41
5	1513.57	203	220.40	469.74

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↪ Tolls based on local info & constant do not lose much

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How did we obtain this result?

1. Structure of optimal tolls: optimal tolls are linear
2. LP to characterize efficiency of linear tolls
3. LP to compute optimal tolls

Optimal local tolls are linear maps

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$$\text{PoA} = \sup_{\text{set of instances}} \left(\frac{\text{total traveltime in worst equilibrium}}{\text{minimum total traveltime}} \right)$$

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Set of instances:

- any graph

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for given bases in $B = \{b_1(x), \dots, b_m(x)\}$

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Local tolling scheme: $\tau_e = T(\ell_e)$

Optimal local tolls are linear maps

$$\text{PoA}(B, n, T) = \sup_{\text{set of instances}} \left(\frac{\text{total traveltime in worst equilibrium}}{\text{minimum total traveltime}} \right)$$

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Claim: There exists a **local optimal tolling** T^{opt} that is **linear**, i.e.,

$$T^{\text{opt}}(\ell_e) = T^{\text{opt}}\left(\sum_j \alpha_j^e \cdot b_j\right) = \sum_j \alpha_j^e \cdot T^{\text{opt}}(b_j)$$

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▷ finding $T^{\text{opt}}(b_j)$ is sufficient!

Computing efficiency of given linear tolls

Computing efficiency of given linear tolls

[Paccagnan, et al.]

Theorem: given $b_1(x), \dots, b_m(x)$, and linear tolls T , let $f_j = b_j + T(b_j)$.

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$$\text{PoA}(B, n, T) = 1/C^*$$

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$$C^* = \max_{\nu \in \mathbb{R}_{\geq 0}, \rho \in \mathbb{R}} \rho$$

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$$\text{s.t. } b_j(x+z)(x+z) - \rho b_j(x+y)(x+y) + \nu [f_j(x+y)y - f_j(x+y+1)z] \geq 0$$

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$$\forall j \in \{1, \dots, m\}$$

Computing efficiency of given linear tolls

[Paccagnan, et al.]

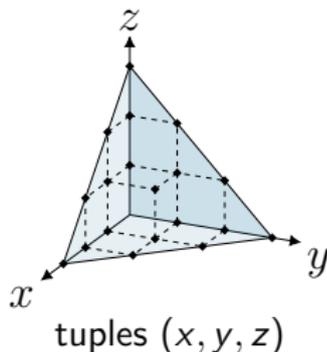
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Computing efficiency of given linear tolls

[Paccagnan, et al.]

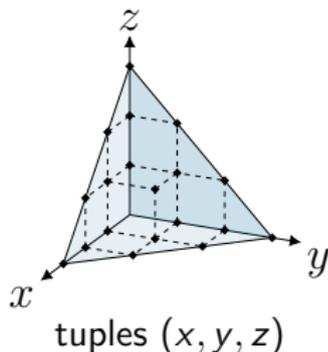
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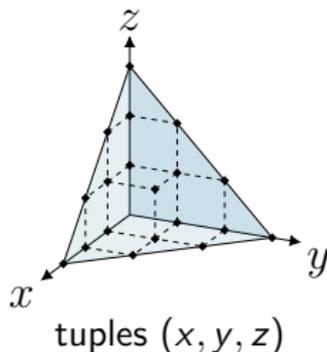
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4. massage and take the dual



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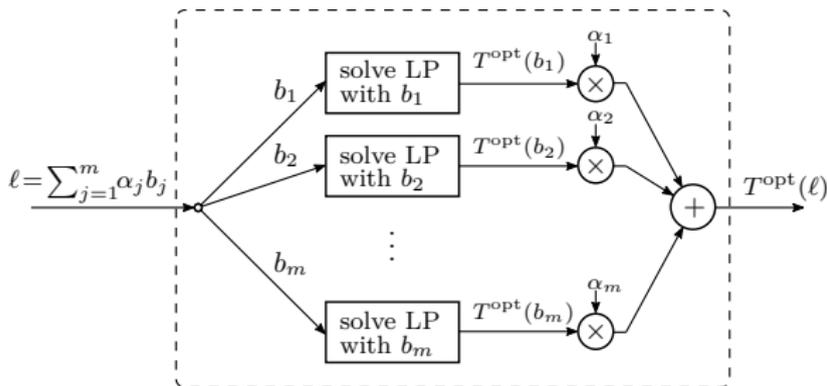
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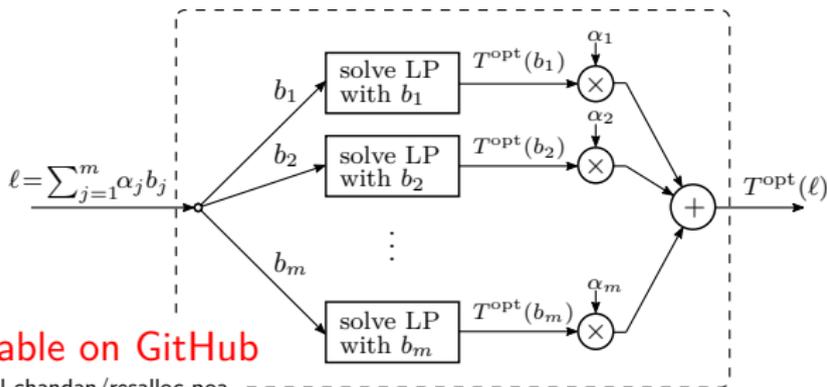
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↪ code available on GitHub

github.com/rahul-chandan/resalloc-poa

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- constraints on tolls
- carrots vs sticks
- knowledge on the latency functions
- ...